Dynamo Action in Spiral Galaxies

Luke Chamandy

University of Cape Town/University of Western Cape, South Africa

Presenting my thesis work done at the Inter-University Centre for Astronomy and Astrophysics, Pune, India

Supervised by: Kandaswamy Subramanian (IUCAA)

Collaborators: Anvar Shukurov (Newcastle), Katherine Stoker (Newcastle), Alice Quillen (Rochester)

Cosmic Magnetic Fields, Krakow

October 20, 2014

Observational Motivation













The mean emf \mathcal{E}

First Order Smoothing Approximation

$$\begin{pmatrix} \frac{\partial}{\partial t} + \frac{1}{\tau} \end{pmatrix} \boldsymbol{\mathcal{E}} = (\alpha \overline{\boldsymbol{B}} - \eta_{\mathbf{t}} \boldsymbol{\nabla} \times \overline{\boldsymbol{B}}) \frac{1}{\tau_{c}} \qquad \tau_{c} \simeq \tau \simeq l/u$$

$$\boldsymbol{\alpha}_{\mathbf{k}} \simeq -\frac{1}{3} \tau_{\mathbf{c}} \overline{\mathbf{u} \cdot (\boldsymbol{\nabla} \times \mathbf{u})} \qquad \eta_{\mathbf{t}} \simeq \frac{1}{3} \tau_{\mathbf{c}} \overline{\boldsymbol{u}^{2}} \qquad \boldsymbol{\alpha} = \boldsymbol{\alpha}_{\mathbf{k}} + \boldsymbol{\alpha}_{\mathbf{m}} \qquad \boldsymbol{\alpha}_{\mathbf{m}} \simeq \frac{1}{3} \tau_{\mathbf{c}} \frac{\mathbf{b} \cdot (\boldsymbol{\nabla} \times \mathbf{b})}{4\pi\rho}$$



The mean emf \mathcal{E}

Minimal τ Approximation

$$\begin{pmatrix} \frac{\partial}{\partial t} + \frac{1}{\tau} \end{pmatrix} \boldsymbol{\mathcal{E}} = (\alpha \overline{\boldsymbol{B}} - \eta_{t} \boldsymbol{\nabla} \times \overline{\boldsymbol{B}}) \frac{1}{\tau_{c}} \qquad \tau_{c} \simeq \tau \simeq l/u$$

$$\alpha_{k} \simeq -\frac{1}{3} \tau_{c} \overline{\boldsymbol{u} \cdot (\boldsymbol{\nabla} \times \boldsymbol{u})} \qquad \eta_{t} \simeq \frac{1}{3} \tau_{c} \overline{\boldsymbol{u}^{2}} \qquad \alpha = \alpha_{k} + \alpha_{m} \qquad \alpha_{m} \simeq \frac{1}{3} \tau_{c} \frac{\overline{\boldsymbol{b} \cdot (\boldsymbol{\nabla} \times \boldsymbol{b})}}{4\pi\rho}$$



The mean emf \mathcal{E}

Minimal τ Approximation

$$\begin{pmatrix} \frac{\partial}{\partial t} + \frac{1}{\tau} \end{pmatrix} \boldsymbol{\mathcal{E}} = (\alpha \overline{\boldsymbol{B}} - \eta_{t} \boldsymbol{\nabla} \times \overline{\boldsymbol{B}}) \frac{1}{\tau_{c}} \qquad \tau_{c} \simeq \tau \simeq l/u$$

$$\alpha_{k} \simeq -\frac{1}{3} \tau_{c} \overline{\boldsymbol{u} \cdot (\boldsymbol{\nabla} \times \boldsymbol{u})} \qquad \eta_{t} \simeq \frac{1}{3} \tau_{c} \overline{\boldsymbol{u}^{2}} \qquad \alpha = \alpha_{k} + \alpha_{m} \qquad \alpha_{m} \simeq \frac{1}{3} \tau_{c} \frac{\overline{\boldsymbol{b} \cdot (\boldsymbol{\nabla} \times \boldsymbol{b})}}{4\pi\rho}$$

Dynamo equation for \overline{B}

Limit of $\tau \to 0$

$$\frac{\partial^2 \overline{B}}{\partial t^2} + \frac{\partial \overline{B}}{\partial t} = \boldsymbol{\nabla} \times (\overline{U} \times \overline{B} + \alpha \overline{B} - \eta_t \boldsymbol{\nabla} \times \overline{B}) + \tau \boldsymbol{\nabla} \times \left(\overline{U} \times \frac{\partial \overline{B}}{\partial t} - \eta_t \boldsymbol{\nabla} \times \overline{B}\right) + \tau \boldsymbol{\nabla} \times \left(\overline{U} \times \frac{\partial \overline{B}}{\partial t} - \eta_t \boldsymbol{\nabla} \times \overline{B}\right) + \tau \boldsymbol{\nabla} \times \left(\overline{U} \times \frac{\partial \overline{B}}{\partial t} - \eta_t \boldsymbol{\nabla} \times \overline{B}\right) + \tau \boldsymbol{\nabla} \times \left(\overline{U} \times \frac{\partial \overline{B}}{\partial t} - \eta_t \boldsymbol{\nabla} \times \overline{B}\right) + \tau \boldsymbol{\nabla} \times \left(\overline{U} \times \frac{\partial \overline{B}}{\partial t} - \eta_t \boldsymbol{\nabla} \times \overline{B}\right) + \tau \boldsymbol{\nabla} \times \left(\overline{U} \times \frac{\partial \overline{B}}{\partial t} - \eta_t \boldsymbol{\nabla} \times \overline{B}\right) + \tau \boldsymbol{\nabla} \times \left(\overline{U} \times \frac{\partial \overline{B}}{\partial t} - \eta_t \boldsymbol{\nabla} \times \overline{B}\right) + \tau \boldsymbol{\nabla} \times \left(\overline{U} \times \frac{\partial \overline{B}}{\partial t} - \eta_t \boldsymbol{\nabla} \times \overline{B}\right) + \tau \boldsymbol{\nabla} \times \left(\overline{U} \times \frac{\partial \overline{B}}{\partial t} - \eta_t \boldsymbol{\nabla} \times \overline{B}\right) + \tau \boldsymbol{\nabla} \times \left(\overline{U} \times \frac{\partial \overline{B}}{\partial t} - \eta_t \boldsymbol{\nabla} \times \overline{B}\right) + \tau \boldsymbol{\nabla} \times \left(\overline{U} \times \frac{\partial \overline{B}}{\partial t} - \eta_t \boldsymbol{\nabla} \times \overline{B}\right) + \tau \boldsymbol{\nabla} \times \left(\overline{U} \times \frac{\partial \overline{B}}{\partial t} - \eta_t \boldsymbol{\nabla} \times \overline{B}\right) + \tau \boldsymbol{\nabla} \times \left(\overline{U} \times \frac{\partial \overline{B}}{\partial t} - \eta_t \boldsymbol{\nabla} \times \overline{B}\right) + \tau \boldsymbol{\nabla} \times \left(\overline{U} \times \frac{\partial \overline{B}}{\partial t} - \eta_t \boldsymbol{\nabla} \times \overline{B}\right) + \tau \boldsymbol{\nabla} \times \left(\overline{U} \times \frac{\partial \overline{B}}{\partial t} - \eta_t \boldsymbol{\nabla} \times \overline{B}\right) + \tau \boldsymbol{\nabla} \times \left(\overline{U} \times \frac{\partial \overline{B}}{\partial t} - \eta_t \boldsymbol{\nabla} \times \overline{B}\right) + \tau \boldsymbol{\nabla} \times \left(\overline{U} \times \frac{\partial \overline{B}}{\partial t} - \eta_t \boldsymbol{\nabla} \times \overline{B}\right) + \tau \boldsymbol{\nabla} \times \left(\overline{U} \times \frac{\partial \overline{B}}{\partial t} - \eta_t \boldsymbol{\nabla} \times \overline{B}\right) + \tau \boldsymbol{\nabla} \times \left(\overline{U} \times \frac{\partial \overline{B}}{\partial t} - \eta_t \boldsymbol{\nabla} \times \overline{B}\right) + \tau \boldsymbol{\nabla} \times \left(\overline{U} \times \frac{\partial \overline{B}}{\partial t} - \eta_t \boldsymbol{\nabla} \times \overline{B}\right) + \tau \boldsymbol{\nabla} \times \left(\overline{U} \times \frac{\partial \overline{B}}{\partial t} - \eta_t \boldsymbol{\nabla} \times \overline{B}\right) + \tau \boldsymbol{\nabla} \times \left(\overline{U} \times \frac{\partial \overline{B}}{\partial t} - \eta_t \boldsymbol{\nabla} \times \overline{B}\right) + \tau \boldsymbol{\nabla} \times \left(\overline{U} \times \frac{\partial \overline{B}}{\partial t} - \eta_t \boldsymbol{\nabla} \times \overline{B}\right) + \tau \boldsymbol{\nabla} \times \left(\overline{U} \times \frac{\partial \overline{B}}{\partial t} - \eta_t \boldsymbol{\nabla} \times \overline{B}\right) + \tau \boldsymbol{\nabla} \times \left(\overline{U} \times \frac{\partial \overline{B}}{\partial t} - \eta_t \boldsymbol{\nabla} \times \overline{B}\right) + \tau \boldsymbol{\nabla} \times \left(\overline{U} \times \frac{\partial \overline{B}}{\partial t} - \eta_t \boldsymbol{\nabla} \times \overline{B}\right) + \tau \boldsymbol{\nabla} \times \left(\overline{U} \times \frac{\partial \overline{B}}{\partial t} - \eta_t \boldsymbol{\nabla} \times \overline{B}\right) + \tau \boldsymbol{\nabla} \times \left(\overline{U} \times \frac{\partial \overline{B}}{\partial t} - \eta_t \boldsymbol{\nabla} \times \overline{B}\right) + \tau \boldsymbol{\nabla} \times \left(\overline{U} \times \frac{\partial \overline{B}}{\partial t} - \eta_t \boldsymbol{\nabla} \times \overline{B}\right) + \tau \boldsymbol{\nabla} \times \left(\overline{U} \times \frac{\partial \overline{B}}{\partial t} - \eta_t \boldsymbol{\nabla} \times \overline{B}\right) + \tau \boldsymbol{\nabla} \times \left(\overline{U} \times \frac{\partial \overline{B}}{\partial t} - \eta_t \boldsymbol{\nabla} \times \overline{B}\right) + \tau \boldsymbol{\nabla} \times \left(\overline{U} \times \frac{\partial \overline{B}}{\partial t} - \eta_t \boldsymbol{\nabla} \times \overline{B}\right) + \tau \boldsymbol{\nabla} \times \left(\overline{U} \times \overline{B}\right) + \tau \boldsymbol{\nabla}$$



The mean emf \mathcal{E}

Minimal τ Approximation

$$\begin{pmatrix} \frac{\partial}{\partial t} + \frac{1}{\tau} \end{pmatrix} \boldsymbol{\mathcal{E}} = (\alpha \overline{\boldsymbol{B}} - \eta_{t} \boldsymbol{\nabla} \times \overline{\boldsymbol{B}}) \frac{1}{\tau_{c}} \qquad \tau_{c} \simeq \tau \simeq l/u$$

$$\alpha_{k} \simeq -\frac{1}{3} \tau_{c} \overline{\boldsymbol{u} \cdot (\boldsymbol{\nabla} \times \boldsymbol{u})} \qquad \eta_{t} \simeq \frac{1}{3} \tau_{c} \overline{\boldsymbol{u}^{2}} \qquad \alpha = \alpha_{k} + \alpha_{m} \qquad \alpha_{m} \simeq \frac{1}{3} \tau_{c} \frac{\overline{\boldsymbol{b} \cdot (\boldsymbol{\nabla} \times \boldsymbol{b})}}{4\pi\rho}$$

Dynamo equation for \overline{B}

General case of finite au

$$\tau \frac{\partial^2 \overline{B}}{\partial t^2} + \frac{\partial \overline{B}}{\partial t} = \nabla \times (\overline{U} \times \overline{B} + \alpha \overline{B} - \eta_t \nabla \times \overline{B}) + \tau \nabla \times \left(\overline{U} \times \frac{\partial \overline{B}}{\partial t}\right)$$

- Effects of order $\Gamma \tau \ll 1$.
- Effects of order $\Omega_p \tau \sim 0.2 0.4 \sim (10 25)^\circ$.

The Dynamical α -Quenching Non-Linearity



- Magnetic helicity: Measure of twist & writhe or, equivalently, linkage in the field.
- Magnetic helicity is very well conserved in a closed system.
- If the initial helicity= 0, then growth of large-scale helicity ⇒ growth of oppositely signed small-scale helicity.
- This small-scale helicity back-reacts via the Lorentz force to quench the dynamo.

The Dynamical α -Quenching Non-Linearity



- Magnetic helicity: Measure of twist & writhe or, equivalently, linkage in the field.
- Magnetic helicity is very well conserved in a closed system.
- If the initial helicity= 0, then growth of large-scale helicity ⇒ growth of oppositely signed small-scale helicity.
- This small-scale helicity back-reacts via the Lorentz force to quench the dynamo.

Evolution equation for $\alpha_{\rm m}$ (Subramanian & Brandenburg 2006, Shukurov et al. 2006) $\frac{\partial \alpha_{\rm m}}{\partial t} = -\frac{2\eta_{\rm t}}{l^2} \left(\frac{\boldsymbol{\mathcal{E}} \cdot \overline{\boldsymbol{B}}}{B_{e\alpha}^2} + \frac{\alpha_{\rm m}}{R_{\rm m}} \right) - \nabla \cdot \boldsymbol{\mathcal{F}}, \qquad \boldsymbol{\mathcal{F}} = \overline{\boldsymbol{U}} \alpha_{\rm m} - \kappa_{\rm t} \boldsymbol{\nabla} \alpha_{\rm m} + \dots$ $\alpha = \alpha_{k} + \alpha_{m}$ source Ohmic flux advective diffusive other term dissipation term flux flux fluxes?

Inputs: l, u, $\Omega(r)$, $\overline{U}_z(z)$, h, $\rho(r)$, κ_{t}

Sur, Shukurov & Subramanian 2007 Chamandy, Shukurov, Subramanian & Stoker 2014

Inputs:
$$l, u, \Omega(r), \overline{U}_{z}(z), h, \rho(r), \kappa_{t}$$

Useful: $D = \frac{\alpha_{k}h^{3}}{\eta_{t}^{2}} \frac{d\Omega}{d\ln r}, \quad \alpha_{k} = \frac{l^{2}}{h}\Omega, \quad \eta_{t} = \frac{1}{3}lu, \quad R_{U} \equiv \frac{\overline{U}_{z}h}{\eta_{t}}, \quad R_{\kappa} \equiv \frac{\kappa_{t}}{\eta_{t}}, \quad t_{d} \equiv \frac{h^{2}}{\eta_{t}}.$
Outputs: $\frac{\langle \overline{B} \rangle}{\sqrt{4\pi\rho u^{2}}} \simeq \frac{l}{h}\sqrt{R_{U} + \pi^{2}R_{\kappa}}\sqrt{\frac{D}{D_{c}} - 1}, \quad D_{c} = -\frac{\pi^{5}}{32}\left(1 + \frac{R_{U}}{\pi^{2}}\right)^{2} \quad (\text{no-z approx.}),$

Inputs:
$$l, u, \Omega(r), \overline{U}_{z}(z), h, \rho(r), \kappa_{t}$$

Sur, Shukurov & Subramanian 2007
Chamandy, Shukurov, Subramanian & Stoker 2014
Useful: $D = \frac{\alpha_{k}h^{3}}{\eta_{t}^{2}} \frac{d\Omega}{d\ln r}, \quad \alpha_{k} = \frac{l^{2}}{h}\Omega, \quad \eta_{t} = \frac{1}{3}lu, \quad R_{U} \equiv \frac{\overline{U}_{z}h}{\eta_{t}}, \quad R_{\kappa} \equiv \frac{\kappa_{t}}{\eta_{t}}, \quad t_{d} \equiv \frac{h^{2}}{\eta_{t}}.$
Outputs: $\frac{\langle \overline{B} \rangle}{\sqrt{4\pi\rho u^{2}}} \simeq \frac{l}{h}\sqrt{R_{U} + \pi^{2}R_{\kappa}}\sqrt{\frac{D}{D_{c}} - 1}, \quad D_{c} = -\frac{\pi^{5}}{32}\left(1 + \frac{R_{U}}{\pi^{2}}\right)^{2} \quad (\text{no-z approx.}),$
 $\overline{B}_{r} \simeq C_{0}\frac{|D_{c}|}{\Omega t_{d}}\left\{\cos\frac{\pi z}{2h} + \frac{3}{4\pi^{2}}\left(\sqrt{\pi|D_{c}|} - \frac{R_{U}}{2}\right)\cos\frac{3\pi z}{2h} + \frac{R_{U}}{2\pi^{2}}\sum_{n=2}^{\infty}\frac{(-1)^{n}(2n+1)}{n^{2}(n+1)^{2}}\cos\left[\left(n + \frac{1}{2}\right)\frac{\pi z}{h}\right]\right\},$
 $\overline{B}_{\phi} \simeq -C_{0}\sqrt{\frac{4|D_{c}|}{\pi}}\left\{\cos\frac{\pi z}{2h} - \frac{3R_{U}}{8\pi^{2}}\cos\frac{3\pi z}{2h} + \frac{R_{U}}{2\pi^{2}}\sum_{n=2}^{\infty}\frac{(-1)^{n}(2n+1)}{n^{2}(n+1)^{2}}\cos\left[\left(n + \frac{1}{2}\right)\frac{\pi z}{h}\right]\right\} (\text{pert. theory}).$

Inputs:
$$l, u, \Omega(r), \overline{U}_{z}(z), h, \rho(r), \kappa_{t}$$

Useful: $D = \frac{\alpha_{k}h^{3}}{\eta_{t}^{2}} \frac{d\Omega}{d\ln r}, \quad \alpha_{k} = \frac{l^{2}}{h}\Omega, \quad \eta_{t} = \frac{1}{3}lu, \quad R_{U} \equiv \frac{\overline{U}_{z}h}{\eta_{t}}, \quad R_{\kappa} \equiv \frac{\kappa_{t}}{\eta_{t}}, \quad t_{d} \equiv \frac{h^{2}}{\eta_{t}}.$
Outputs: $\frac{\langle \overline{B} \rangle}{\sqrt{4\pi\rho u^{2}}} \simeq \frac{l}{h}\sqrt{R_{U} + \pi^{2}R_{\kappa}}\sqrt{\frac{D}{D_{c}} - 1}, \quad D_{c} = -\frac{\pi^{5}}{32}\left(1 + \frac{R_{U}}{\pi^{2}}\right)^{2} \quad (\text{no-}z \text{ approx.}),$
 $\overline{B}_{r} \simeq C_{0}\frac{|D_{c}|}{\Omega t_{d}}\left\{\cos\frac{\pi z}{2h} + \frac{3}{4\pi^{2}}\left(\sqrt{\pi|D_{c}|} - \frac{R_{U}}{2}\right)\cos\frac{3\pi z}{2h} + \frac{R_{U}}{2\pi^{2}}\sum_{n=2}^{\infty}\frac{(-1)^{n}(2n+1)}{n^{2}(n+1)^{2}}\cos\left[\left(n + \frac{1}{2}\right)\frac{\pi z}{h}\right]\right\},$
 $\overline{B}_{\phi} \simeq -C_{0}\sqrt{\frac{4|D_{c}|}{\pi}}\left\{\cos\frac{\pi z}{2h} - \frac{3R_{U}}{8\pi^{2}}\cos\frac{3\pi z}{2h} + \frac{R_{U}}{2\pi^{2}}\sum_{n=2}^{\infty}\frac{(-1)^{n}(2n+1)}{n^{2}(n+1)^{2}}\cos\left[\left(n + \frac{1}{2}\right)\frac{\pi z}{h}\right]\right\} (\text{pert. theory})$



Dynamical vs. Algebraic Quenching

Algebraic quenching heuristic formula:

$$\alpha = rac{lpha_{\mathrm{k}}}{1 + a(\overline{B}/B_{\mathrm{eq}})^q}$$

with q = 2 and a = 1



Dynamical vs. Algebraic Quenching

Algebraic quenching heuristic formula:

$$\alpha = \frac{\alpha_{\rm k}}{1 + a (\overline{B}/B_{\rm eq})^q}$$
 with $q=2$ and $a=1$

No-z steady-state solution
with
$$\tan p_B \equiv \overline{B}_r / \overline{B}_\phi \ll 1$$



Dynamical vs. Algebraic Quenching

Algebraic quenching heuristic formula:



 $\overline{B}(4 \,\mathrm{kpc}, 0) / B_{\mathrm{eq}}(0, 0)$

• Direct numerical simulation (Gressel, Bendre & Elstner 2013): $\alpha \simeq \alpha_{\rm k} / \left[1 + a (\overline{B} / B_{\rm eq})^2 \right]$ with $q = 2.0 \pm 0.3$ and $a = 27 \pm 14$ \rightarrow Support for dynamical quenching theory.

Magnetic arms and the τ effect



Chamandy, Subramanian & Shukurov 2013a, b

Magnetic arms and the τ effect



Chamandy, Subramanian & Shukurov 2013a, b

Magnetic arms and the τ effect



Importance of Outflows and of Spiral Evolution



Chamandy, Shukurov & Subramanian 2014

Chamandy, Subramanian & Quillen 2014

Importance of Outflows and of Spiral Evolution



Chamandy, Shukurov & Subramanian 2014

Importance of Outflows and of Spiral Evolution



Summary

- Approximate analytical solutions are available and may be useful as a first line of attack or for comparison with observations/simulations.
- The algebraic quenching formula can, in disc galaxies, be understood as an approximation of dynamical quenching theory; this form of quenching seems to be supported by direct simulations.
- The τ effect can lead to phase shifts of magnetic arms from gaseous/stellar arms of $-(1 \text{ to } 2)\Omega_{\rm p}\tau \sim -10^{\circ}$ to -40° . This may help to explain the phase shifts observed in several galaxies.
- Outflows are expected to be concentrated in the gaseous/stellar spiral arms; this can lead naturally to the concentration of regular fields in the interarm regions.
- Characterizing the nature of spiral evolution is crucial for determining the structure and evolution of magnetic arms. Observations showing magnetic arms aligned with gaseous/stellar arms over several kpc seem to favour transient (winding-up) density wave models.